

# EE 561: Digital Control Systems

Spring 2017

## Quiz # 3

Time: 20 min

Name: \_\_\_\_\_

Roll #: \_\_\_\_\_

### Question # 1

(10 marks)

Consider the following sampled-data system for regulating the continuous-time integrator (all variables are scalar)

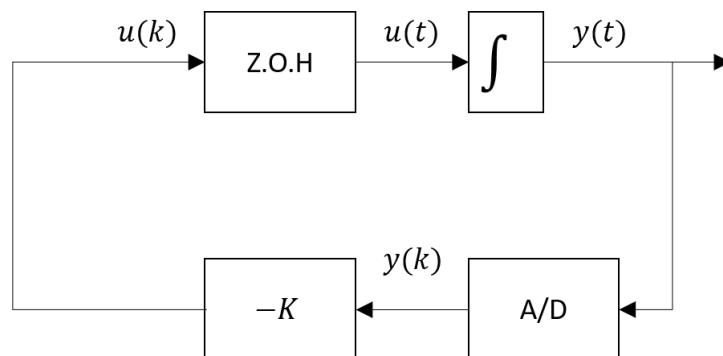


Figure 1: Sampled data system for Question 1.

(a) 3 marks

Write down a state space representation of the continuous-time plant. Assume  $x(t) = y(t)$ .

**(b) 4 marks**

Determine the state space representation of the discrete-time system.

**(c) 3 marks**

What value of  $K$  should be selected in order to get a deadbeat response? (Remember a deadbeat response is one where all closed-loop poles are at zero).